Image-based Face Detection and Recognition:

“State of the Art”

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Abstract

Face recognition from image or video is a popular topic in biometrics research. Many public places usually have surveillance cameras for video capture and these cameras have their significant value for security purpose. It is widely acknowledged that the face recognition have played an important role in surveillance system as it doesn’t need the object’s cooperation. The actual advantages of face based identification over other biometrics are uniqueness and acceptance. As human face is a dynamic object having high degree of variability in its appearance, that makes face detection a difficult problem in computer vision. In this field, accuracy and speed of identification is a main issue.

The goal of this paper is to evaluate various face detection and recognition methods, provide complete solution for image based face detection and recognition with higher accuracy, better response rate as an initial step for video surveillance. Solution is proposed based on performed tests on various face rich databases in terms of subjects, pose, emotions, race and light.

Keywords: Face Detection, Face Recognition, Biometrics, Face Identification.

1. Introduction

Over the last few decade lots of work is been done in face detection and recognition [14] as it’s a best way for person identification [16] because it doesn’t require human cooperation [15] so that it became a hot topic in biometrics. Since lots of methods are introduced for detection [6,7,8,12,13] and recognition [8,9,10,11] which considered as a milestone. Although these methods are used several times for the same purpose separately for limited number of datasets in past but there is no work found who provides overall performance evaluation of said methods altogether by testing them on tough datasets like [1,2,3,4,5], details of datasets will be provided in section IV.

In current paper we developed a system for the said method’s evaluation as first milestone for video based face detection and recognition for surveillance. The overview of current system is demonstrated in figure 1.

Fig. 1 System’s overview.

1.1 Paper Organization

The following paper discuss about face detection methods in section II, section III discuss about face recognition methods based on the results of section II; result summery
has been provided in the form of tables. Section IV provides summery about datasets that are been used in section II and section III. Section V is a conclusion phase.

2. Face Detection


Haar-like [7] features are evaluated through the use of a new image representation that generates a large set of features and uses the boosting algorithm AdaBoost [6] to reduce degenerative tree of the boosted classifiers for robust and fast interferences only simple rectangular Haar-like [7] features are used that provides a number of benefits like sort of ad-hoc domain knowledge is implied as well as a speed increase over pixel based systems, suggestive to Haar [7] basis functions equivalent to intensity difference readings are quite easy to compute. Implementation of a system that used such features would provide a feature set that was far too large, hence the feature set must be only restricted to a small number of critical features which is achieved by boosting algorithm, Adaboost [6].

The original LBP [8] operator labels the pixels of an image by thresholding the 3-by-3 neighborhood of each pixel with the center pixel value and considering the result as a binary number. Each face image can be considered as a composition of micro-patterns which can be effectively detected by the LBP [8] operator. To consider the shape information of faces, they divided face images into N small non-overlapping regions $T_0, T_1, ..., T_N$. The LBP [8] histograms extracted from each sub-region are then concatenated into a single, spatially enhanced feature histogram defined as:

$$H_i = \sum_{x,y} I(f(x,y) = i) I((x,y) / T_j)$$

where $i = 0, ..., L-1; j = 0, ..., N-1$. The extracted feature histogram describes the local texture and global shape of face images.

<table>
<thead>
<tr>
<th>Dataset</th>
<th>Detection</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Adaboost</td>
</tr>
<tr>
<td>Haar</td>
<td>99.31%</td>
</tr>
<tr>
<td>LBP</td>
<td>98.33%</td>
</tr>
<tr>
<td>HOG</td>
<td>98.31%</td>
</tr>
<tr>
<td>[1]</td>
<td>96.94%</td>
</tr>
<tr>
<td>[2]</td>
<td>90.65%</td>
</tr>
<tr>
<td>Mean</td>
<td>96.70%</td>
</tr>
</tbody>
</table>

Moreover system is been tested on datasets [1,2,3,4,5] and based on above demonstrated system, results are demonstrated below:

SVM [12] classifier is been used with HOG [13] features for face detection. HOG [13] greatly outperforms wavelets and degree of smoothing before calculating gradients damages, results emphasizes much of the available information is from sudden edges at fine scales that blurring this for reducing the sensitivity to spatial position is a mistake. Gradients should be calculated at the finest available scale in the current pyramid layer and strong local contrast normalization is essential for good results. Whereas SVM [12] are formulated to solve a classical two class problem which returns a binary value, the class of the object. To train our SVM [12] algorithm, we formulate the problem in a difference space that explicitly captures the dissimilarity between two facial images. The results summery of above methods are stated below.
3. Face Recognition

Eigenfaces [9] considered as 2-D face recognition problem, faces will be mostly upright and frontal. That’s why 3-D information about the face is not required that reduces complexity by a significant bit. It convert the face images into a set of basis functions which essentially are the principal components of the face images seeks directions in which it is more efficient to represent the data. This is mainly useful for decrease the computational effort. Linear discriminant analysis is primarily used here to reduce the number of features to a more manageable number before recognition because face is represented by a large number of pixel values. Each of the new dimensions is a linear combination of pixel values, which form a template. The linear combinations obtained using Fisher’s linear discriminant are called Fisherfaces [10]. LBP [8] is an order set of binary comparisons of pixel intensities between the center pixel and its eight surrounding pixels.

$$LBP (x_a, y_a) = \sum_{n=0}^{7}s(i_n - i_a)2^n$$

Where $i_n$ corresponds to the value of the center pixel $(x_a, y_a)$, $i_m$ to the value of eight surrounding pixels, function $f(x)$ is defined as:

$$f(x) = \begin{cases} 
1 & \text{if } x \geq 0 \\
0 & \text{if } x < 0 
\end{cases}$$


<table>
<thead>
<tr>
<th>Dataset</th>
<th>Recognition</th>
<th>PCA</th>
<th>LDA</th>
<th>LBP</th>
<th>Gabor</th>
</tr>
</thead>
<tbody>
<tr>
<td>[1]</td>
<td></td>
<td>72.10%</td>
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<td>85.93%</td>
<td>93.49%</td>
</tr>
<tr>
<td>[2]</td>
<td></td>
<td>69.87%</td>
<td>76.61%</td>
<td>80.47%</td>
<td>89.76%</td>
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<tr>
<td>[3]</td>
<td></td>
<td>70.95%</td>
<td>78.34%</td>
<td>84.14%</td>
<td>92.68%</td>
</tr>
<tr>
<td>[4]</td>
<td></td>
<td>74.79%</td>
<td>81.93%</td>
<td>86.45%</td>
<td>96.91%</td>
</tr>
<tr>
<td>[5]</td>
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<td>68.04%</td>
<td>73.21%</td>
<td>77.69%</td>
<td>88.93%</td>
</tr>
<tr>
<td>Mean</td>
<td></td>
<td>71.15%</td>
<td>77.90%</td>
<td>82.94%</td>
<td>92.35%</td>
</tr>
</tbody>
</table>

4. Dataset

Five datasets been used for above experiments. In dataset [1], face collection with plain green background; no head scale and light variation but having minor changes in head turn, tilt, slant, position of face and considerable change in expressions.

In dataset [2], face collection with red curtain background, variation is caused by shadows as subject moves forward, having minor changes in head turn, tilt and slant; large head scale variation; some expression variation, translation in position of face and image lighting variation as subject moves forward, significant lighting changes occur on faces moment due to the artificial lighting arrangement. In dataset [3], face collection with complex background; large head scale variation; minor variations in head turn, tilt, slant and expression; some translation in face position and significant light variation because of object moment in artificial light. In dataset [4], face collection with plain background; small head scale variation; considerable variation in head turn, tilt, slant and major variation in expression; minor translation in face position and light variation. In dataset [5], face collection with constant background having minor head scale variation and light variation; huge variation in turn, tilt, slant, expression and face position.

5. Conclusion

In current work we developed the system to evaluate the face detection and recognition methods which are
considered to be a bench mark. Some methods performed consistently over different datasets whereas other methods behave very randomly however based on average experimental results performance is evaluated, five datasets been used for this purpose. Face detection and recognition method’s result summery is provided in table 1 and table 2 respectively whereas datasets summery is provided in table 3. In current system Haar-like [7] features reported relatively well but it has much false detection than LBP [8] which could be consider being a future work in surveillance to reduce false detection in Haar-like [7] features and for the recognition part gabor [11] is reported well as it’s qualities overcomes datasets complexity.

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References